

TUESDAY, JUNE 2

	Time (CET)	Session
	09:00 – 10:30	Keynote Tutorial 1: Learning Agile Vision-based Quadrotor Flight: from Simulation to Real-world Adaption, Speakers: Davide Scaramuzza, Rudolf Reiter, Ismail Geles
	11:00 – 12:30	Keynote Session: Autonomous Vehicles & Navigation Speakers: Johannes Betz (TUM), Michael Milford (QUT), Aniket Bera (Purdue University), Hesheng Wang (Shanghai Jiao Tong University)
Room L1.2.3 CW	14:00 – 14:50	Plenary 1: Can GOFE and Code-as-Policy Close the 100,000-Year “Data Gap” in Robot Manipulation? Ken Goldberg, UC Berkeley and Ambi Robotics
	15:00 – 16:30	Keynote Tutorial 2: The Open Motion Planning Library (OMPL 2.0) Lydia Kavraki, Thai Duong, Theodoros Tyrovouzis, Clayton Ramsey, Nikki Hart, Arden Knoll
	16:45 – 18:15	Medical & Healthcare Robotics Speakers: Eric Diller (University of Toronto), Fanny Ficuciello (University of Naples Federico II), Tiantian Xu (Shenzhen Institutes of Advanced Technology), Haoyong Yu (National University of Singapore)

WEDNESDAY, JUNE 3

	Time (CET)	Session
	09:00 – 10:30	Industrial Keynote: EIT Manufacturing presenting Blueflight, Dominik Kersch: Automating Documentation Artifacts in Safety Critical Processes; Beckhoff Automation GmbH, Thomas Morscher-Unger: ATRO – The future of robotics is modular; Franka Robotics, Sven Parusel: Translating Innovation: Closing the Gap in Physical AI Deployment; Amazon, Aaron Parness: Amazon’s Robotic Manipulation; Infineon Technologies AG, Maurizio Incurvati: The road towards a new era of actuators for humanoids; Robosense, Xiansheng Yang: Breaking Boundaries in 3D Perception, Empowering Spatial Intelligence; PaXini Tech, Li Jiale: Build a Bridge Between AI Intelligence and the Physical World; Galbot, He Wang: Towards the AlphaGo and ChatGPT Moments of Embodied AI; Encord, Max Dolan: Diagnosing the Data Problem in Robotics?; Flexiv Robotics, Shuyun Chung: Bridging the Last Millimeter in Contact-Rich Manipulation
Room L1.2.3 CW	11:00 – 12:30	Keynote Session: Robot Perception & Spatial AI Speakers: Ayoung Kim (Seoul National University), Luca Carlone (Massachusetts Institute of Technology), Maren Bennewitz (University of Bonn), Timothy Barfoot (University of Toronto)
	14:00 – 14:50	Plenary 2: Natural Revolution: Biological Principles for Frugal and Sustainable Robotics Barbara Mazzolai, Istituto Italiano di Tecnologia (IIT)
	15:00 – 16:30	Keynote Tutorial 3: Building, Running and Deploying Modern Software Tools for Robotics Speakers: Peter Corke, Tobias Fischer
	16:45 – 18:15	Keynote Session: Manipulation, Humanoids, Embodied Design Speakers: Jeannette Bohg (Stanford University), Kento Kawaharazuka (The University of Tokyo), Nikos Tsagarakis (Istituto Italiano di Tecnologia), Yuke Zhu (UT-Austin)

ADDITIONAL INFORMATION

- **Admission:** Free
- **Contact:** For more details, visit <https://2026.ieee-icra.org/satellite-conference-centers/>
- **Dates:** June 2–3, 2026
- **Location:** Poznan University of Technology
- **Room:** L123 Lecture Center (library)
- **Time Zone:** All times are in Central European Time (CET, UTC+1)
- **Registration:** <https://forms.gle/zwd2aJsEdEmUrkWh8>

